

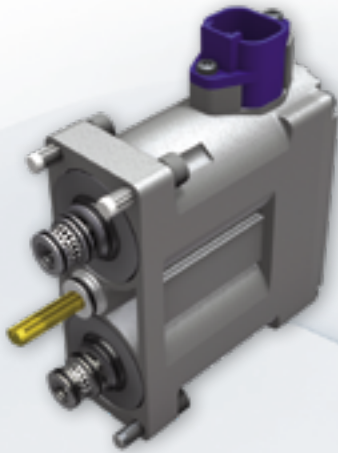
# TECNORD

SERVOCOMANDI E REGOLAZIONE

## Multidrom MLT FD-5

### PRINCIPLE OF OPERATION

The MLT-FD5/D electro-hydraulic proportional actuator has been designed to shift a directional control valve spool either directly (FL version) or by means of a servo-piston mechanically connected to it (SP version). The internal closed loop position control configuration of the MLT-FD5/D makes the valve spool achieve the desired position with accuracy levels approaching the performance of a servo-valve, by continuously comparing the set-point of a remote control device (e.g. potentiometer, joystick, Machine Management System controller) with the feed-back signal generated by a high-precision hall effect position transducer.



### FEATURES

#### Two Independent Proportional Valves

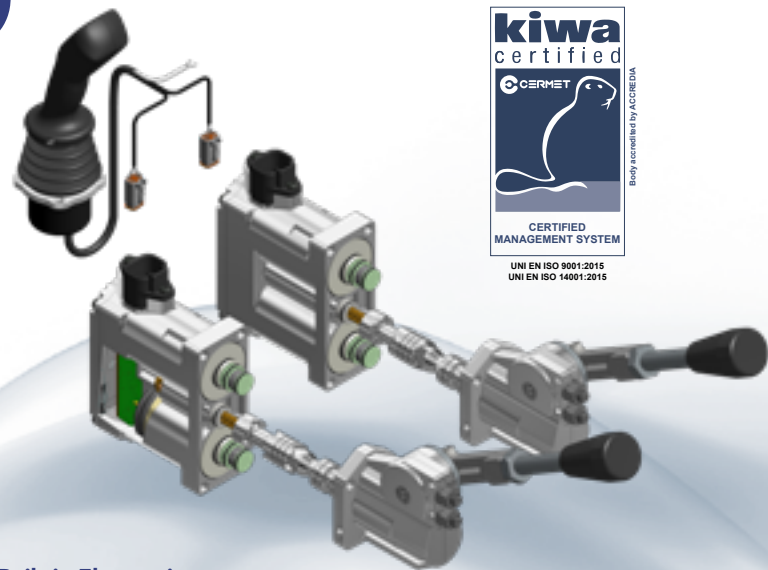
**Control Configuration:** bidirectional with MOTOR SPOOL center position for fail-safe return to neutral in case of power loss.

**Flow Rate:** 0.2 to 0.5 lt/min. max. flow requirement under normal conditions.

**Work Pressure:** 12 to 35 bar.

#### Hall Effect/Contactless Spool Position Sensor

- Excellent linear control on 100% of spool travel.
- 8 mm standard control stroke from each side of NEUTRAL/13 mm for FLOAT position in one direction only.
- No "Cross Talking" between adjacent work sections.



### Built-in Electronics

**MLT-FD5-D (digital):** microprocessor-based actuator.

Choice between different types of control:

- Analog or ratiometric control signal, with following auxiliary signals available:

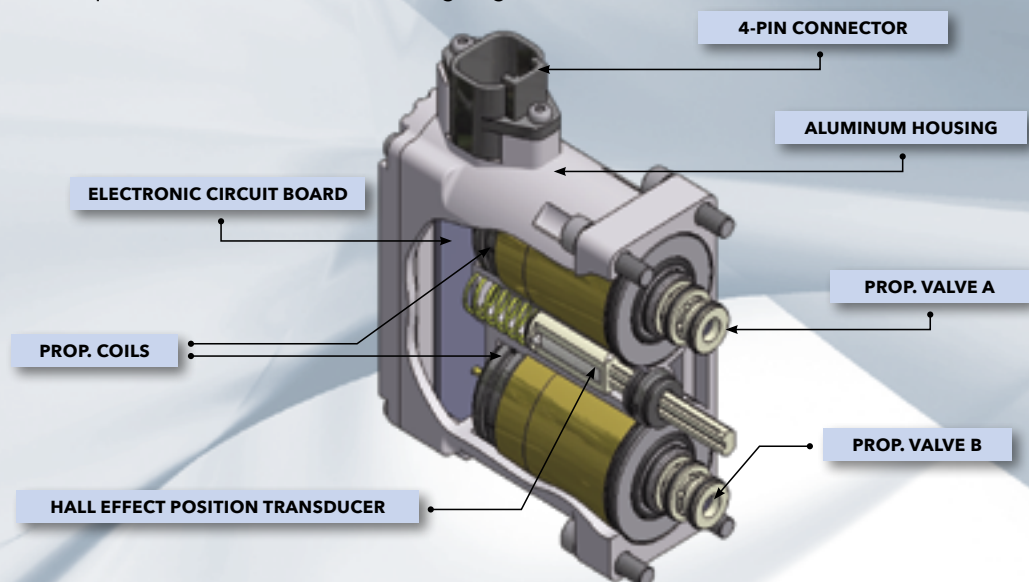
- ✓ spool position feedback.
- ✓ 5V for external potentiometer or joystick.

- CANbus control (J1939 or CANopen protocols).

**MLT-FD5-0 (on-off):** 12 or 24V version.

### APPLICATIONS

- High performance proportional control of stackable or monoblock directional control valves.
- Proportional control of variable displacement pumps and motors.
- Engine governor RPM controls.



## CONTROL CHARACTERISTIC OF MLT-FD5 PROPORTIONAL ACTUATOR (ANALOG OPERATING MODE)

### SPOOL STROKE A

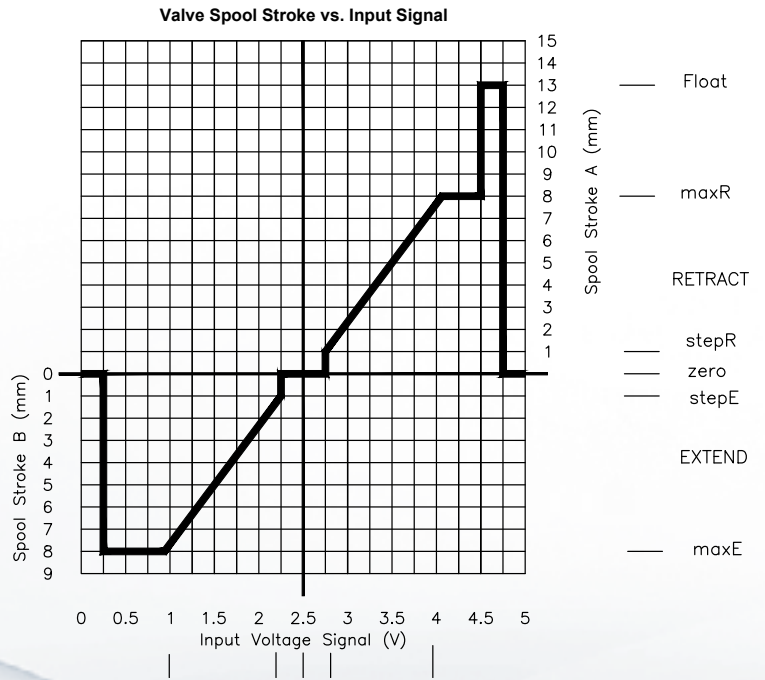
When the input voltage signal fed to the MLT-FD5 actuator is maintained within 2.25 and 2.75V, the directional valve spool is at rest (Neutral Dead Band). When  $V_{in} = 2.75V$ , the spool steps up from NEUTRAL to MINIMUM FLOW control position. A linear ramp from MIN. to MAX. spool stroke will follow by increasing  $V_{in}$  from 2.75 to 4.1V. At  $V_{in} = 4.50V$ , the spool is brought into its FLOAT POSITION, if present. By decreasing the input voltage from 4.1 to 2.75V, the spool stroke is linearly reduced and after the oil flow is fully shut-off, a step-down from MINIMUM FLOW to NEUTRAL position takes place.

### SPOOL STROKE B

Same as for STROKE A, by varying  $V_{in}$  from 2.25 to 0.9V, the spool will go from NEUTRAL to MAX. STROKE in the opposite direction.

### ALARM / FAIL - SAFE MODE

An input voltage variation beyond the calibration range ( $<0.25V$  or  $>4.75V$ ) will bring the system into an ALARM mode, urging the spool to return to its NEUTRAL position until  $V_{in}$  is brought back to its nominal control range.



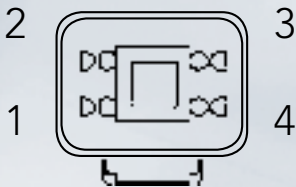
### HYDRAULIC SPECIFICATIONS

- Max. supply pressure..... 35 bar
- Min. supply pressure ..... 12 bar
- Max. back pressure..... 1.5 bar
- Pilot flow requirement..... 0.2 lt/section
- Oil temperature range ..... -20/+95°C
- Oil viscosity range ..... 3-650 cSt
- Filtration ..... 18/15/10 (ISO 4406)

### ELECTRICAL SPECIFICATIONS

- Operating voltage ..... 8-30 VDC
- Max. current consumption ..... 750mA/section
- Operating temperature ..... -40/+125°C
- Analog input impedance ..... >40 kOhm
- Typical ctrl pot. resistance..... 1-10 kOhm
- Degree of protection..... IP 68

### CONNECTOR PINOUT (FRONT VIEW)



#### D/C0

1. +Power Supply
2. CANL
3. CANH
4. -Power Supply (GND)

#### D/A0

1. +Power Supply
2. Do not Connect
3. Control Signal
4. -Power Supply (GND)

#### D/A5

1. +Power Supply
2. +5V Aux. Supply voltage
3. Control Signal
4. -Power Supply (GND)

#### D/AF

1. +Power Supply
2. Sensor Feedback Output
3. Control Signal
4. -Power Supply (GND)

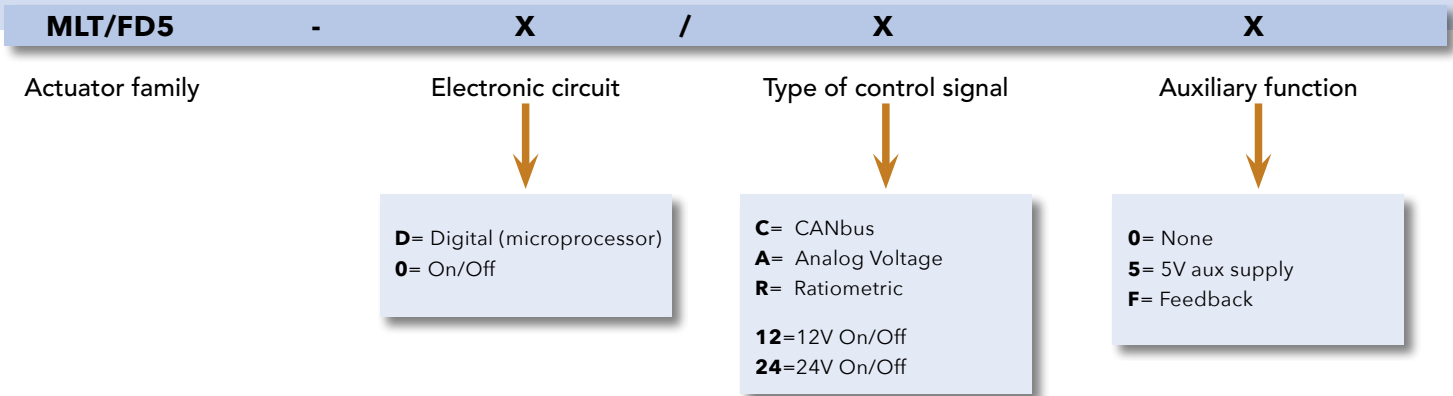
#### D/R0

1. +V Power Supply
2. Do not Connect
3. Control Signal
4. -V Power Supply (GND)

#### 0/12 - 0/24

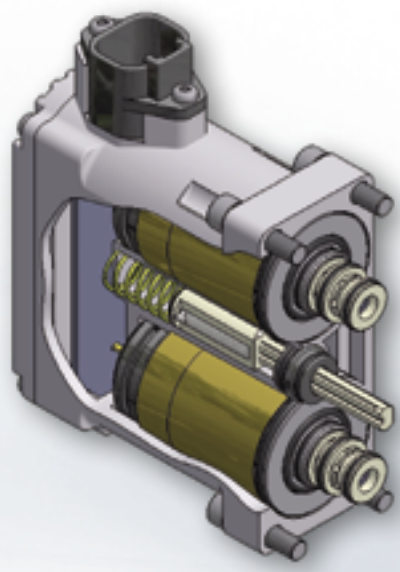
1. +Power Supply coil A
2. -Power Supply (GND) coil A
3. +Power Supply coil B
4. -Power Supply (GND) coil B

ACTUATORS SELECTION GUIDE



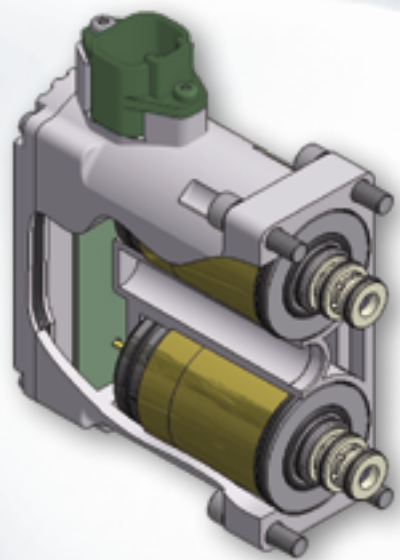
AVAILABLE CONFIGURATIONS AND MODEL DESIGNATION

- MLT/FD5-D/C0**  
Proportional actuator  
Digital electronics  
CANbus control (J1939)
- MLT/FD5-D/A0**  
Proportional actuator  
Digital electronics  
Analog control signal (e.g. Potentiometer)
- MLT/FD5-D/A5**  
Proportional actuator  
Digital electronics  
Analog control signal (e.g. Potentiometer)  
+5V auxiliary power supply for the control potentiometer
- MLT/FD5-D/AF**  
Proportional actuator  
Digital electronics  
Analog control signal (e.g. Potentiometer)  
Feedback output (spool position): 0-5V
- MLT/FD5-D/R0**  
Proportional actuator  
Digital electronics  
Ratiometric control signal (% of supply voltage)



**Digital Actuator**  
Black connector

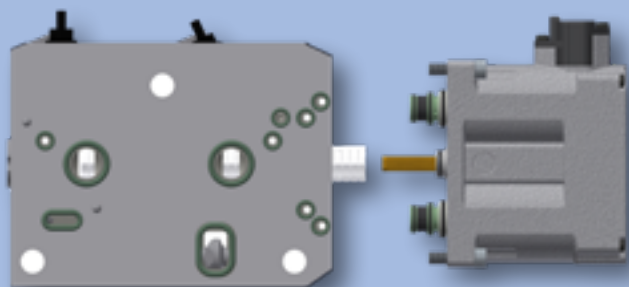
- MLT/FD5-0-12**  
On/Off actuator, 12V coils
- MLT/FD5-0-24**  
On/Off actuator, 24V coils



**On/Off Actuator**  
(without hall effect sensor)  
Blue connector: 12V  
Green connector: 24V

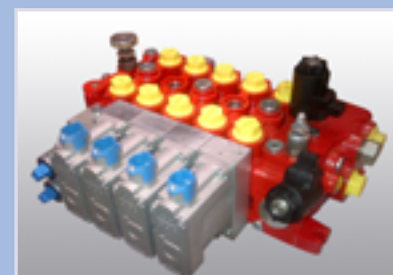
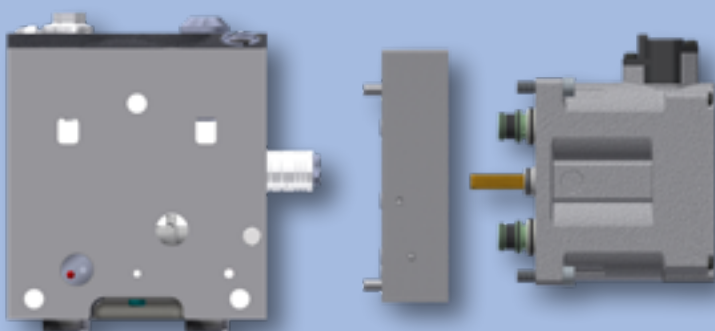
## INSTALLATION OPTIONS

### DIRECT FLANGED MOUNTING STYLE



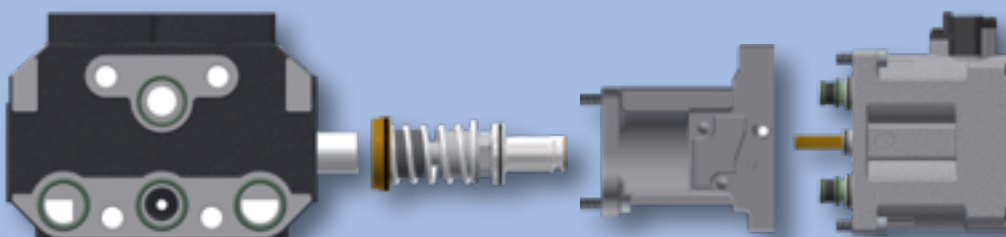
TDV100LT

### ADAPTER PLATE MOUNTING STYLE



BUCHER HDS34

### ADAPTER PLATE WITH BUILT-IN D/A SERVO PISTON



BOSCH-REXROTH  
MOD. SX14



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