

JOYSTICK FAMILY & TYPE	MAIN BASE CONFIGURATION	YY / XX AXES CONTROL CONFIG.	TYPE OF GRIP	GRIP CONFIGURATION	CONNECTOR TYPE
<b>JHM</b> Heavy duty / Multi-axis hall effect type joystick controller	<b>L2S</b> Single axis, bidirectional	<b>ANL</b> Analog signal 0.5>2.5>4.5 VDC power supply range = 5 VDC ±5%	<b>IL</b> Cylindrical knob	Refer to the grip ordering information for <b>z z e k k</b> axes (push-buttons & proportional controls on grips)	<b>3</b> Flying leads 25 cm length
	<b>L4C</b> Dual axes, cross movement	<b>ANH</b> Analog signal 0.5>2.5>4.5 VDC power supply range = 8-32 VDC	<b>IC</b> Cylindrical		<b>4</b> Male connector, 12 poles, Deutsch DT04-12P, 25 cm cable length
	<b>L4D</b> Dual axes, all diagonals	<b>AVS</b> Center tap output signal with digital directional signals	<b>IE</b> Multi-function ergonomic		<b>5</b> Male connector, 4 poles, Deutsch DT04-4P, 25 cm cable length (for CANbus version only)
		<b>MLT</b> adjustable output signal for closed loop prop. actuators	<b>MS</b> Multi-function ergonomic symmetric		<b>6</b> Male connector, 6 poles, Deutsch DT04-6P, 25 cm cable length
		<b>RTM</b> adjustable output signal for closed loop prop. actuators	<b>MG</b> Multi-function ergonomic right hand		<b>7</b> Male connector, 8 poles, Deutsch DT04-8P, 25 cm cable length
		<b>PWM</b> Pulse with modulation current output factory preset or set via PC	<b>HL</b> Multi-function ergonomic left hand		
	<b>TCN</b> 1 PWM output in combination with up to 4 on-off channels	<b>HR</b> Multi-function ergonomic right hand			
		<b>CAN</b> CANbus version for connection to CANbus line J1939 protocol			

*Note:*  
for TCN, PWM and MLT versions, a 4 poles, Deutsch DT04-4P connector is always included

EXAMPLE:

JHM-L4D/ANH-6  
BASE



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MS/0000/2FPR/R000  
GRIP



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**JHM-L4D/ANH-MS/0000/2FPR/R000-6**  
COMPLETE JOYSTICK  
(with 6 poles Deutsch connector)